## **General Description**

The LTC863x family of single-, dual-, and quad- channel operational amplifiers represents a new generation of general-purpose, low-power op-amps. Featuring rail- to-rail input and output (RRIO) swings, low quiescent current (typical 700  $\mu$ A) combined with a wide bandwidth (7 MHz) makes this family very attractive for a variety of battery-powered applications that require a good balance between cost and performance, such as motor phase current sensing, photodiode amplification, barcode scanners and white goods. The low input bias current supports these amplifiers to be used in applications with mega-ohm source impedances. The robust design of the LTC863x amplifiers provides ease-of-use to the circuit designer: unity-gain stability with capacitive loads of up to 500 pF, integrated RF/EMI rejection filter, no phase reversal in overdrive conditions, and high electro-static discharge (ESD) protection (3 kV HBM). The LTC863x amplifiers are optimized for operation at voltages as low as +2.3 V (± 1.15 V) and up to +5.5 V (± 2.75 V) over the extended temperature range of -40 °C to +125 °C.

The LTC8631 (single) is available in SOT23-5L package. The LTC8632 (dual) is offered in both SOIC-8L, DFN-8L and MSOP8L packages. The quad-channel LTC8634 is offered in 14- lead SOIC package.

## **Features and Benefits**

- Wide Unity-Gain Bandwidth: 7 MHz
- High Slew Rate: 10 V/μs
- Fast Settling: 0.3 μs to 0.1%
- Low Input Offset Voltage: ±0.7 mV
- Single 2.3 V to 5.5 V Power Supply Range
- Rail-to-Rail Input and Output
- Internal RF/EMI Filter
- Low Supply Current: 700 μA at 5V Supply Per Amplifier
- Extended Temperature Range: -40°C to +125°C

## **Applications**

- Motor Phase Current Sense
- Photodiode Amplification
- Active Filters
- Driving A/D Converters
- Portable Equipment
- Battery-Powered Instrumentation



# LTC8631, LTC8632, LTC8634 7MHz, High Slew Rate, RRIO, CMOS Amplifier

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## Ordering Information<sup>(1)</sup>

Part Number	Package Type	Package Quantity	ECO Class <sup>(2)</sup>	Mark Code <sup>(3)</sup>
LTC8631XT5/R6	S0T23-5L	Tape and Reel, 3 000	Green (RoHS & no Sb/Br)	C31
LTC8632XS8/R8	SOIC-8L	Tape and Reel, 4 000	Green (RoHS & no Sb/Br)	C32
LTC8632XF8/R6	DFN2x2-8L	Tape and Reel, 3 000	Green (RoHS & no Sb/Br)	C32
LTC8632XV8/R6	MSOP-8L	Tape and Reel, 4 000	Green (RoHS & no Sb/Br)	C32
LTC8634XS14/R5	SOIC-14L	Tape and Reel, 2 500	Green (RoHS & no Sb/Br)	C34

\* Preview Status (Not for MP stage, pls contact with us if you have request)

(1) Please contact to your Linearin representative for the latest availability information and product content details.

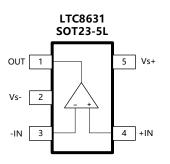
(2) Eco Class - The planned eco-friendly classification: Pb-Free (RoHS) or Green (RoHS & Halogen Free).

(3) There may be multiple device markings, a varied marking character of "x", or additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

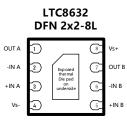


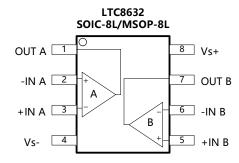
LTC8631, LTC8632, LTC8634 7MHz, High Slew Rate, RRIO, CMOS Amplifier

## Pin Configuration (Top View)



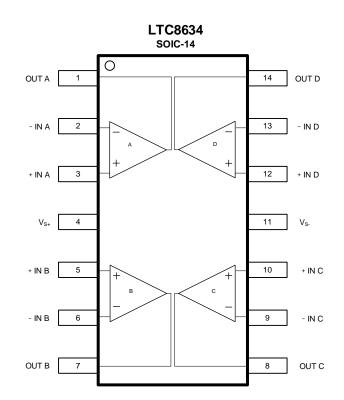
PIN Name	S0T23-5L	Description
OUT	1	Amplifier output.
V <sub>s</sub> .	2	Negative power supply. It is normally tied to ground. It can also be tied to a voltage other than ground as long as the voltage between $V_{S+}$ and $V_{S-}$ is from 2.3 V to 5.5 V.
-IN	3	Inverting input of the amplifier. The voltage range is from (Vs- – 0.1 V) to (Vs+ + 0.1 V).
+IN	4	Non-inverting input of the amplifier. This pin has the same voltage range as -IN.
V <sub>s+</sub>	5	Positive power supply. The voltage is from 2.3 V to 5.5 V. Split supplies are possible as long as the voltage between $V_{S^*}$ and $V_{S^-}$ is from 2.3 V to 5.5 V.





PIN Name	SOIC-8L / MSOP-8L / DFN2x2-8L	Description
OUT A	1	Amplifier A output.
-IN A	2	Inverting input A of the amplifier. The voltage range is from (Vs- – 0.1 V) to (Vs+ + 0.1 V).
+IN A	3	Non-inverting input of the amplifier. This pin has the same voltage range as –IN A.
V <sub>s-</sub>	4	Negative power supply. It is normally tied to ground. It can also be tied to a voltage other than ground as long as the voltage between $V_{S+}$ and $V_{S-}$ is from 2.3 V to 5.5 V.
+IN B	5	Non-inverting input of the amplifier. This pin has the same voltage range as –IN B.
-IN B	6	Inverting input B of the amplifier. The voltage range is from (Vs- – 0.1 V) to (Vs+ + 0.1 V).
OUT B	7	Amplifier B output.
V <sub>5</sub> ,	8	Positive power supply. The voltage is from 2.3 V to 5.5 V. Split supplies are possible as long as the voltage between $V_{S^+}$ and $V_{S^-}$ is from 2.3 V to 5.5 V.





PIN Name	SOIC-14L	Description
OUT A	1	Amplifier A output.
-IN A	2	Inverting input A of the amplifier. The voltage range is from (V <sub>S-</sub> – 0.1 V) to (V <sub>S+</sub> + 0.1 V).
+IN A	3	Non-inverting input of the amplifier. This pin has the same voltage range as –IN A.
V <sub>s+</sub>	4	Positive power supply. The voltage is from 2.3 V to 5.5 V. Split supplies are possible as long as the voltage between $V_{S+}$ and $V_{S-}$ is from 2.3 V to 5.5 V.
+IN B	5	Non-inverting input of the amplifier. This pin has the same voltage range as –IN B.
-IN B	6	Inverting input B of the amplifier. The voltage range is from (Vs- – 0.1 V) to (Vs+ + 0.1 V).
OUT B	7	Amplifier B output.
OUT C	8	Amplifier C output.
-IN C	9	Inverting input C of the amplifier. The voltage range is from (V <sub>S-</sub> – 0.1 V) to (V <sub>S+</sub> + 0.1 V).
+IN C	10	Non-inverting input of the amplifier. This pin has the same voltage range as -IN C.
V <sub>s-</sub>	11	Negative power supply. It is normally tied to ground. It can also be tied to a voltage other than ground as long as the voltage between $V_{S+}$ and $V_{S-}$ is from 2.3 V to 5.5 V.
+IN D	12	Non-inverting input of the amplifier. This pin has the same voltage range as –IN D.
-IN D	13	Inverting input D of the amplifier. The voltage range is from (V_S- – 0.1 V) to (V_S+ + 0.1 V).
OUT D	14	Amplifier D output.

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## Limiting Value

P-6

In accordance with the Absolute Maximum Ratin System (IEC60134).

Parameter	Absolute Maximum Rating
Supply Voltage, Vs+ to Vs-	10 V
Signal Input Terminals: Voltage	$V_{\text{S-}}$ – 0.5 V to $V_{\text{S+}}$ + 0.5 V
Signal Input Terminals: Current	± 10 mA
Output Short-Circuit	Continuous
Storage Temperature Range, T <sub>sta</sub>	–65 °C to +150 °C
Junction Temperature, T	150 °C
Lead Temperature Range (Soldering 10 sec)	260 °C

## **ESD Ratings**

Parameter	Level	UNIT
Human body model (HBM), per ESDA/JEDEC JS-001-2023 <sup>(1)</sup>	$\pm$ 3 000	V
Machine Model (MM) , per JESD22-A115C-2010	±150	V

 JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible if necessary precautions are taken.

## **Thermal Information**

Thermal Metric		Package	Level	Unit
		SOT23-5L	190	
		SOIC-8L	125	
θ <sub>JA</sub>	Package Thermal Resistance	MS0P-8L	216	°C <b>/W</b>
		DFN2x2-8L	94	
		SOIC-14L	115	



## **Electrical Characteristics**

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit			
OFFSET VOLTAGE									
Input offset voltage	Vos			±0.7	±2.5	mV			
Offset voltage drift	V <sub>os</sub> TC	T <sub>A</sub> = -40 to +125 °C		±1	- r	µV/°C			
Power supply rejection	DCDD	V <sub>S</sub> = 2.0 to 5.5 V, V <sub>CM</sub> < V <sub>S+</sub> -2 V	90	106	·				
ratio	PSRR	T <sub>A</sub> = -40 to +125 °C	85	,		dB			
INPUT BIAS CURRENT									
	, ,			1					
Input bias current	lв	T <sub>A</sub> = +85 °C	150						
		T <sub>A</sub> = +125 °C		900		-			
Input offset current	los			1		pА			
NOISE									
Input voltage noise density	en	f = 10 kHz		35	·	nV/√Hz			
INPUT VOLTAGE									
Common-mode voltage range	V <sub>CM</sub>		V <sub>S-</sub> - 0.1		V <sub>S+</sub> + 0.1	V			
		$V_{s}$ = 5.5 V, $V_{CM}$ = -0.1 to 5.6 V	72	85	<u>.</u>	_			
Common-mode rejection ratio	CMRR	$V_{\rm S}$ = 5.5 V, $V_{\rm CM}$ = 0 to 3.4 V, T <sub>A</sub> = -40 to +125 °C	85			— dB			
		V <sub>S</sub> = 2.3 V, V <sub>CM</sub> = -0.1 to 2.4 V 70 82							
		$V_{\rm S}$ = 2.3 V, $V_{\rm CM}$ = 0 to 0.7 V, T <sub>A</sub> = -40 to +125 °C	76						
OPEN-LOOP GAIN									
		$R_{L}$ = 50 kΩ, $V_{0}$ = 0.05 to 3.5 V	93	102		_			
Open-loop voltage gain	<b>A</b>	$R_L$ = 50 kΩ, V <sub>0</sub> = 0.05 to 3.5 V T <sub>A</sub> = -40 to +125 °C	84			−dB			
open-toop vottage gain	AVOL	$R_L$ = 2k $\Omega$ , $V_0$ = 0.15 to 3.5 V	91	100		UD			
		$R_L$ = 2kΩ, V <sub>0</sub> = 0.15 to 3.5 V T <sub>A</sub> = -40 to +125 °C	81						
FREQUENCY RESPONSE				-r					
Gain bandwidth product	GBW			7		MHz			
Slew Rate	SR	G = +1, C <sub>L</sub> = 100 pF, V <sub>0</sub> = 1.5 to 3.5 V		10		V/µs			
Overload recovery time	TOR	V <sub>IN</sub> x Gain > V <sub>S</sub>		0.3	<u>.</u>	μs			
OUTPUT				*					
High output voltage		R <sub>L</sub> = 10 kΩ	V <sub>S+</sub> - 8	V <sub>S+</sub> - 5		_			
swing	V <sub>он</sub>	R <sub>L</sub> = 600 Ω	V <sub>s+</sub> - 180	V <sub>s+</sub> - 140	mV				
Low output voltage	Vol	R <sub>L</sub> = 10 kΩ		Vs₋ +5	Vs- <b>+7</b>	- m\/			
swing	VUL	R <sub>L</sub> = 600 Ω		V <sub>S-</sub> +80	V <sub>S-</sub> +90	−mV			

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## **Electrical Characteristics (Cont.)**

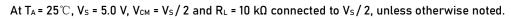
$V_s$ = 5.0 V, $T_A$ = + 25 °C, $V_{CM}$ = $V_s/2$ , $V_0$ = $V_s/2$ , and $R_L$ = 10 k $\Omega$ connected to $V_s/2$ , unless otherwise noted.
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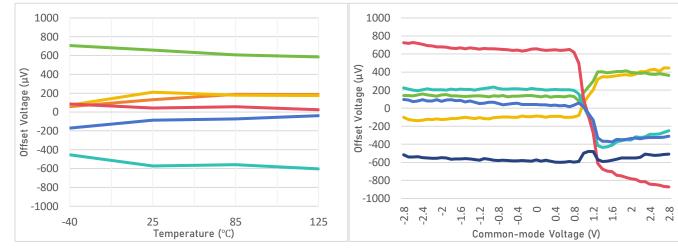
Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Short-circuit current	Isource	D 100	50			— mA
	Isink	R <sub>L</sub> = 10Ω		75		
POWER SUPPLY			·	,		
Operating supply voltage	Vs	T <sub>A</sub> = -40 to +125 °C	2.3		5.5	v
Quiescent current		Vs = 2.5 V		600	700	A
(per amplifier)	la	V <sub>s</sub> = 5.0 V		700	850	—μΑ

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## **Typical Characteristics**







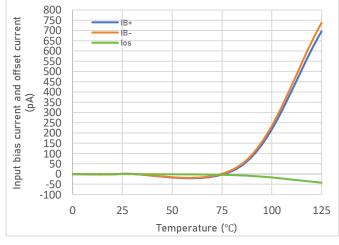


Figure 3. Input Bias Current vs Temperature

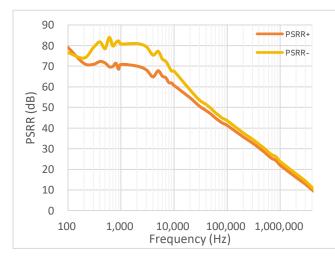
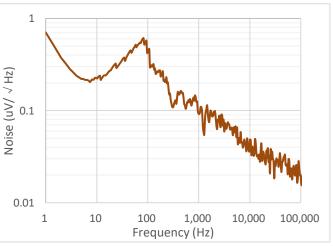


Figure 5. PSRR vs Frequency

Figure 2. Offset Voltage vs Common-mode Voltage





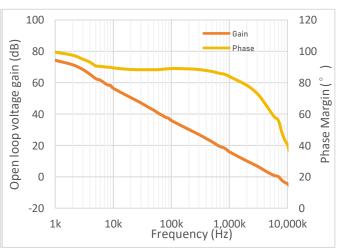
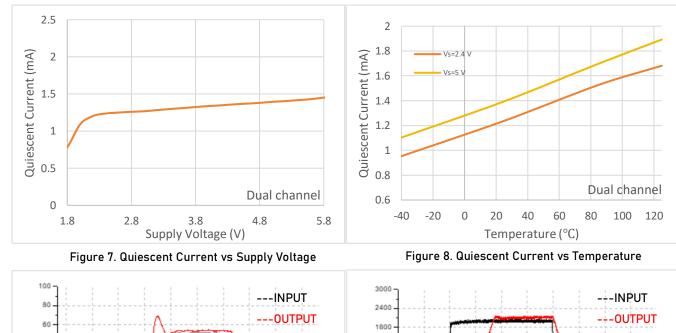


Figure 6. Open Loop Gain and Phase vs Frequency



## Typical Characteristics (Cont.)

At T<sub>A</sub> = 25  $^{\circ}$ C, V<sub>S</sub> = 5.0 V, V<sub>CM</sub> = V<sub>S</sub>/2 and R<sub>L</sub> = 10 k $\Omega$  connected to V<sub>S</sub>/2, unless otherwise noted.



1200

600

-600

-1200

1800

-2400

3000

-500 -250

0

Voltage (mV)

900



TIME (ns)

450 600 750

150 300

-150

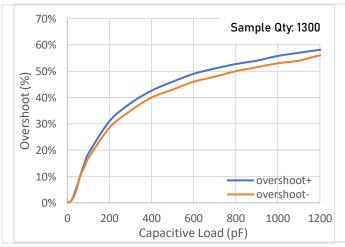




Figure 10. Large Signal Step Response

TIME (ns)

1000 1250 1500 1750 2000

250 500 750



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40

20

0

-20

-40

-60

-80

100

450 -300

Voltage (mV)



## **Detailed Description**

The LTC863x is a family of low-power, rail-to-rail input and output operational amplifiers specifically designed for portable applications. These devices operate from 2.3 V to 5.5 V at the temperature range of -40 °C to +125 °C, are unity-gain stable, and suitable for a wide range of general-purpose applications. The class AB output stage is capable of driving  $\leq$  10 k $\Omega$  loads connected to any point between V<sub>S+</sub> and ground. The input common-mode voltage range includes both rails, and allows the LTC863x family to be used in virtually any single supply application. Rail-to-rail input and output swing significantly increases dynamic range, especially in low-supply applications, and makes them ideal for driving sampling analog-to-digital converters (ADCs).

The LTC863x features 7 MHz bandwidth and 10 V/ $\mu$ s slew rate with only 700  $\mu$ A supply current per amplifier, providing good ac performance at very low power consumption. DC applications are also well served with low input bias current, and an input offset voltage of 0.7 mV typically. The typical offset voltage drift is 1  $\mu$ V/°C, over the full temperature range the input offset voltage changes only 100  $\mu$ V (0.7 mV to 0.8 mV).

## **Operating Voltage**

The LTC863x family is optimized for operation at voltages as low as +2.3 V ( $\pm$ 1.15 V) and up to +5.5 V ( $\pm$ 2.75 V). In addition, many specifications apply from -40 °C to +125 °C. Parameters that vary significantly with operating voltages or temperature are illustrated in the Typical Characteristics graphs.

NOTE: Supply voltages ( $V_{S+}$  to  $V_{S-}$ ) higher than +10 V can permanently damage the device.

#### Rail to rail input

The input common-mode voltage range of the LTC863x series extends 100-mV beyond the negative and positive supply rails. This performance is achieved with a complementary input stage: an N-channel input differential pair in parallel with a P-channel differential pair. The N-channel pair is active for input voltages close to the positive rail, typically  $V_{5*}$ -1.4 V to the positive supply, whereas the P-channel pair is active for inputs from 100-mV below the negative supply to approximately  $V_{5*}$ -1.4 V. There is a small transition region, typically  $V_{5*}$ -1.2 V to  $V_{5*}$ -1 V, in which both pairs are on. This 200-mV transition region can vary up to 200-mV with process variation. Thus, the transition region (both stages on) can range from  $V_{5*}$ -1.4 V to  $V_{5*}$ -1.2 V on the low end, up to  $V_{5*}$ -1 V to  $V_{5*}$ -0.8 V on the high end. Within this transition region, PSRR, CMRR, offset voltage, offset drift, and THD can be degraded compared to device operation outside this region.

The typical input bias current of the LTC863x during normal operation is approximately 1 pA. In overdriven conditions, the bias current can increase significantly. The most common cause of an overdriven condition occurs when the operational amplifier is outside of the linear range of operation. When the output of the operational amplifier is driven to one of the supply rails, the feedback loop requirements cannot be satisfied and a differential input voltage develops across the input pins. This differential input voltage results in activation of parasitic diodes inside the front-end input chopping switches that combine with electromagnetic interference (EMI) filter resistors to create the equivalent circuit. Notice that the input bias current remains within specification in the linear region.

## Input EMI filter and clamp circuit

Figure 1 shows the input EMI filter and clamp circuit. The LTC863x op-amps have internal ESD protection diodes (D1, D2, D3, and D4) that are connected between the inputs and each supply rail. These diodes protect the input transistors in the event of electrostatic discharge and are reverse biased during normal operation. This protection scheme allows voltages as high as approximately 500-mV beyond the rails to be applied at the input of either terminal without causing permanent damage. These ESD protection current-steering diodes also provide in-circuit, input overdrive protection, as long as the current is limited to

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# 

20 mA as stated in the Absolute Maximum Ratings.

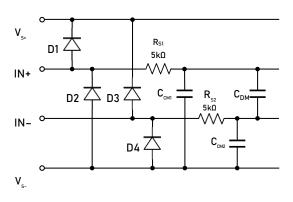


Figure 1. Input EMI Filter and Clamp Circuit

Operational amplifiers vary in susceptibility to EMI. If conducted EMI enters the operational amplifier, the dc offset at the amplifier output can shift from its nominal value when EMI is present. This shift is a result of signal rectification associated with the internal semiconductor junctions. Although all operational amplifier pin functions can be affected by EMI, the input pins are likely to be the most susceptible. The EMI filter of the LTC863x family is composed of two 5 k $\Omega$  input series resistors (R<sub>S1</sub> and R<sub>S2</sub>), two common-mode capacitors (C<sub>CM1</sub> and C<sub>CM2</sub>), and a differential capacitor (C<sub>DM</sub>). These RC networks set the -3 dB low-pass cutoff frequencies at 35 MHz for common-mode signals, and at 22 MHz for differential signals.

## Rail to rail output

Designed as a micro-power, low-noise operational amplifier, the LTC863x delivers a robust output drive capability. A class AB output stage with common-source transistors is used to achieve full rail-to-rail output swing capability. For resistive loads up to 100 k $\Omega$ , the output swings typically to within 5-mV of either supply rail regardless of the power-supply voltage applied. Different load conditions change the ability of the amplifier to swing close to the rails. For resistive loads up to 600  $\Omega$ , the output swings typically to within 140 mV of the positive supply rail and within 80 mV of the negative supply rail.

## Capacitive load and stability

The LTC863x family can safely drive capacitive loads of up to 500 pF in any configuration. As with most amplifiers, driving larger capacitive loads than specified may cause excessive overshoot and ringing, or even oscillation. A heavy capacitive load reduces the phase margin and causes the amplifier frequency response to peak. Peaking corresponds to overshooting or ringing in the time domain. Therefore, it is recommended that external compensation be used if the LTC863x op-amps must drive a load exceeding 500 pF. This compensation is particularly important in the unity-gain configuration, which is the worst case for stability.

A quick and easy way to stabilize the op-amp for capacitive load drive is by adding a series resistor, R<sub>150</sub>, between the amplifier output terminal and the load capacitance, as shown in Figure 2. R<sub>150</sub> isolates the amplifier output and feedback network from the capacitive load. The bigger the R<sub>150</sub> resistor value, the more stable V<sub>OUT</sub> will be. Note that this method results in a loss of gain accuracy because R<sub>150</sub> forms a voltage divider with the R<sub>L</sub>.



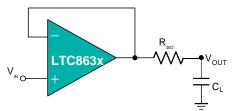


Figure 2. Indirectly Driving Heavy Capacitive Load

An improvement circuit is shown in Figure 3. It provides DC accuracy as well as AC stability. The R<sub>F</sub> provides the DC accuracy by connecting the inverting signal with the output.

The C<sub>F</sub> and R<sub>ISO</sub> serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop.

For no-buffer configuration, there are two other ways to increase the phase margin: (a) by increasing the amplifier's gain, or (b) by placing a capacitor in parallel with the feedback resistor to counteract the parasitic capacitance associated with inverting node.

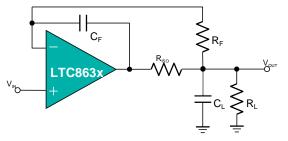


Figure 3. Indirectly Driving Heavy Capacitive Load with DC Accuracy

## **Overload recovery**

Overload recovery is defined as the time required for the operational amplifier output to recover from a saturated state to a linear state. The output devices of the operational amplifier enter a saturation region when the output voltage exceeds the rated operating voltage, either because of the high input voltage or the high gain. After the device enters the saturation region, the charge carriers in the output device require time to return back to the linear state. After the charge carriers return back to the linear state, the device begins to slew at the specified slew rate. Thus, the propagation delay in case of an overload condition is the sum of the overload recovery time and the slew time. The overload recovery time for the LTC863x family is approximately 0.3 µs.

## **EMI rejection ratio**

Circuit performance is often adversely affected by high frequency EMI. When the signal strength is low and transmission lines are long, an op-amp must accurately amplify the input signals. However, all op-amp pins — the non-inverting input, inverting input, positive supply, negative supply, and output pins — are susceptible to EMI signals. These high frequency signals are coupled into an op-amp by various means, such as conduction, near field radiation, or far field radiation. For example, wires and printed circuit board (PCB) traces can act as antennas and pick up high frequency EMI signals.

Amplifiers do not amplify EMI or RF signals due to their relatively low bandwidth. However, due to the nonlinearities of the input devices, op-amps can rectify these out of band signals. When these high frequency signals are rectified, they appear as a dc offset at the output.

The LTC863x op-amps have integrated EMI filters at their input stage. A mathematical method of measuring EMIRR is



defined as follows: *EMIRR = 20 log (V<sub>IN PEAK</sub>/ΔV<sub>OS</sub>)* 

## Input to output coupling

To minimize capacitive coupling, the input and output signal traces should not be parallel. This helps reduce unwanted positive feedback.

## Maximizing performance through proper layout

To achieve the maximum performance of the extremely high input impedance and low offse voltage of the LTC863x opamps, care is needed in laying out the circuit board. The PCB surface must remain clean and free of moisture to avoid leakage currents between adjacent traces. Surface coating of the circuit board reduces surface moisture and provides a humidity barrier, reducing parasitic resistance on the board. The use of guard rings around the amplifier inputs further reduces leakag currents. Figure 4 shows proper guard ring configuration and the top view of a surface-mount layout. The guard ring does not need to be a specific width, but it should form a continuous loop around both inputs. By setting the guard ring voltage equal to the voltage at the non-inverting input, parasitic capacitance is minimized as well. For further reduction of leakage currents, components can be mounted to the PCB using Teflon standoff insulators.

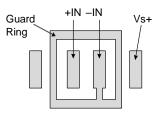


Figure 4. Use a guard ring around sensitive pins

Other potential sources of offset error are thermoelectric voltages on the circuit board. This voltage, also called Seebeck voltage, occurs at the junction of two dissimilar metals and is proportional to the temperature of the junction. The most common metallic junctions on a circuit board are solder-to-board trace and solder-to-component lead. If the temperature of the PCB at one end of the component is different from the temperature at the other end, the resulting Seebeck voltages are not equal, resulting in a thermal voltage error.

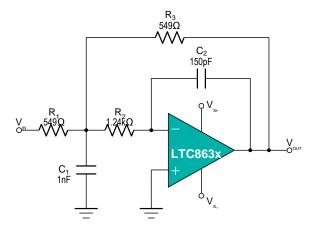
This thermocouple error can be reduced by using dummy components to match the thermoelectric error source. Placing the dummy component as close as possible to its partner ensures both Seebeck voltages are equal, thus canceling the thermocouple error. Maintaining a constant ambient temperature on the circuit board further reduces this error. The use of a ground plane helps distribute heat throughout the board and reduces EMI noise pickup.

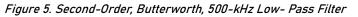


## **Typical Application Circuit**

## Active filter

The LTC863x family is well-suited for active filter applications that require a wide bandwidth, fast slew rate, single-supply operational amplifier. Figure 5 shows a 500 kHz, second-order, low-pass filter using the multiple-feedback (MFB) topology. The components have been selected to provide a maximally-flat Butterworth response. Beyond the cut-off frequency, roll-off is -40 dB/dec. The Butterworth response is ideal for applications that require predictable gain characteristics, such as the anti-aliasing filter used in front of an ADC.





One point to observe when considering the MFB filter is that the output is inverted, relative to the input. If this inversion is not required, or not desired, a non- inverting output can be achieved through one of these options:

- 1. adding an inverting amplifier ;
- 2. adding an additional second-order MFB stage;
- 3. using a non-inverting filter topology, such as the Sallen-Key (shown in Figure 6).

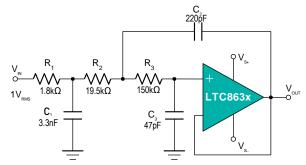


Figure 6. Configured as a Three-Pole, 20-kHz, Sallen- Key Filter

## Motor phase current sensing

The current sensing amplification shown in Figure 7 has a slew rate of  $2\pi fV_{PP}$  for the output of sine wave signal, and has a slew rate of  $2fV_{PP}$  for the output of triangular wave signal. In most of motor control systems, the PWM frequency is at 10 kHz to 20 kHz, and one cycle time is 100 µs for a 10 kHz of PWM frequency. In current shunt monitoring for a motor phase, the phase current is converted to a phase voltage signal for ADC sampling. This sampling voltage signal must be settled before entering the ADC. As the Figure 7 shown, the total settling time of a current shunt monitor circuit includes: the rising edge delay time (t<sub>SR</sub>) due to the op-amp's slew rate, and the measurement settling time (t<sub>SET</sub>). For a 2- shunt solution of motor phase current sensing, if the minimum duty cycle of the PWM is defined at 5%, and the t<sub>SR</sub> is required at 20% of a total time window for a phase



current monitoring, in case of a 3.3 V motor control system (3.3 V MCU with 12-bit ADC), the op- amp's slew rate should be more than:

3.3V / (100µs× 5% × 20%) = 3.3 V/µs

At the same time, the op-amp's bandwidth should be much greater than the PWM frequency, like 10 time at least.

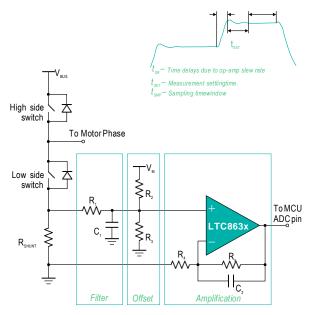


Figure 7. Current Shunt Monitor Circuit

## **Differential amplifier**

The circuit shown in Figure 8 performs the difference function. If the resistors ratios are equal  $R_4/R_3 = R_2/R_1$ , then:  $V_{OUT} = (V_p - V_n) * R_2/R_1 + V_{REF}$ 

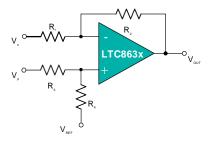
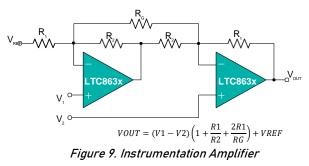


Figure 8. Differential Amplifier

Instrumentation amplifier



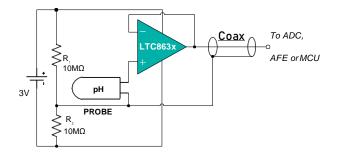
The LTC863x family is well suited for conditioning sensor signals in battery-powered applications. Figure 9 shows a two op-amp instrumentation amplifier, using the LTC863x op-amps. The circuit works well for applications requiring rejection of

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common-mode noise at higher gains. The reference voltage ( $V_{REF}$ ) is supplied by a low-impedance source. In single voltage supply applications, the  $V_{REF}$  is typically  $V_S/2$ .

## **Buffered chemical sensors**

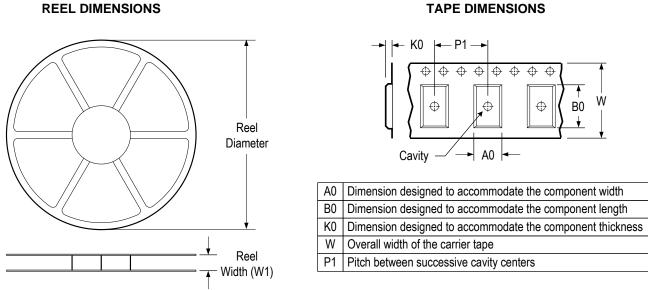


All components contained within the pH probe Figure 10. Buffered pH Probe

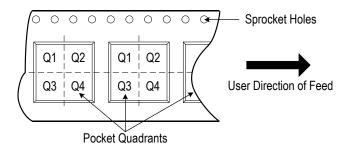
The LTC863x family has input bias current in the pA range. This is ideal in buffering high impedance chemical sensors, such as pH probes. As an example, the circuit in Figure 10 eliminates expansive low-leakage cables that that is required to connect a pH probe (general purpose combination pH probes, e.g Corning 476540) to metering ICs such as ADC, AFE and/or MCU. A LTC863x op-amp and a lithium battery are housed in the probe assembly. A conventional low-cost coaxial cable can be used to carry the op-amp's output signal to subsequent ICs for pH reading.



## **Tape and Reel Information**



## **QUADRANT ASSIGNMENTS FOR PIN 1 ORIETATION IN TAPE**



## \* All dimensions are nominal

Device	Package Type	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin 1 Quadrant
LTC8631XT5/R6	SOT23	5	3 000	178	9.0	3.3	3.2	1.5	4.0	8.0	Q3
LTC8632XS8/R8	SOIC	8	4 000	330	12.4	6.6	5.3	2.0	8.0	12.0	Q1
LTC8632XF8/R6	DFN	8	3 000	178	9.0	2.3	2.3	1.1	4.0	7.9	Q1
LTC8632XV8/R6	MSOP	8	3 000	330	12.4	5.0	3.5	2.0	8.0	12.0	Q1
LTC8634XS14/R5	SOIC	14	2 500	330	12.4	6.5	9.5	2.0	8.0	16.0	Q1

## TAPE DIMENSIONS

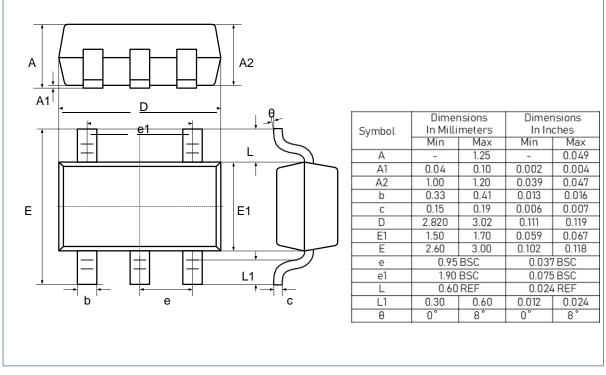


## P-19

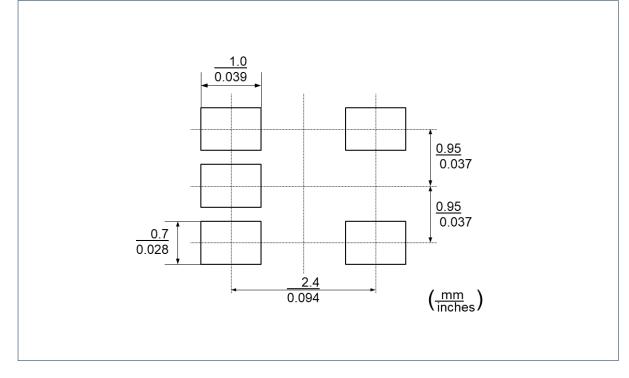
# LTC8631, LTC8632, LTC8634 7MHz, High Slew Rate, RRIO, CMOS Amplifier

## Package Outlines

## DIMENSIONS, SOT23-5L



## RECOMMENDED SOLDERING FOOTPRINT, SOT23-5L

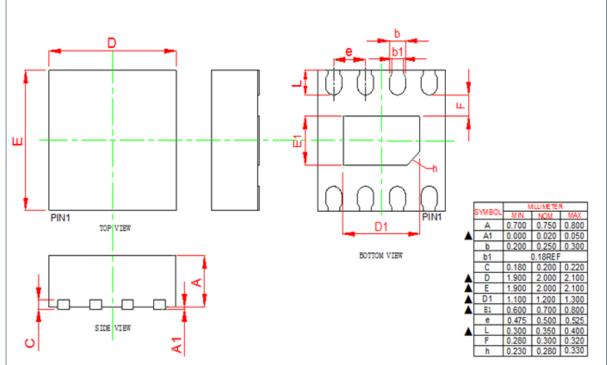


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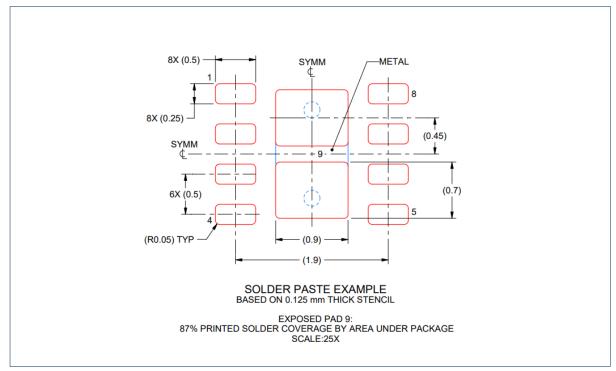
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## Package Outlines (cont.)





## RECOMMENDED SOLDERING FOOTPRINT, DFN-8L



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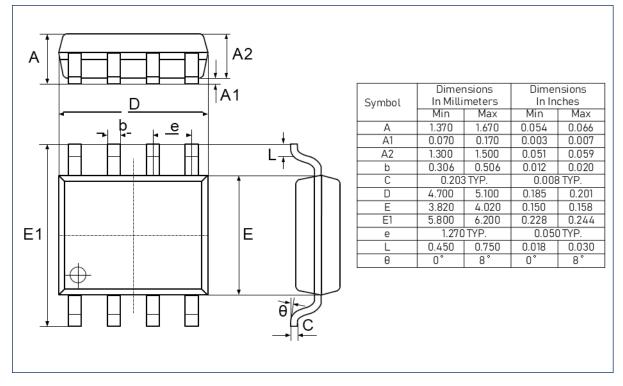


INEARIN

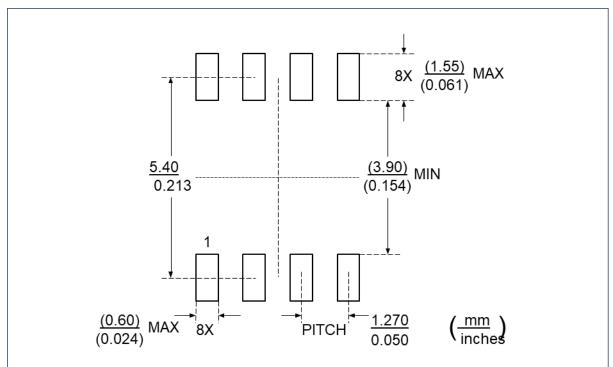
# LTC8631, LTC8632, LTC8634 7MHz, High Slew Rate, RRIO, CMOS Amplifier

## Package Outlines (cont.)

## DIMENSIONS, SOIC-8L



## RECOMMENDED SOLDERING FOOTPRINT, SOIC-8L

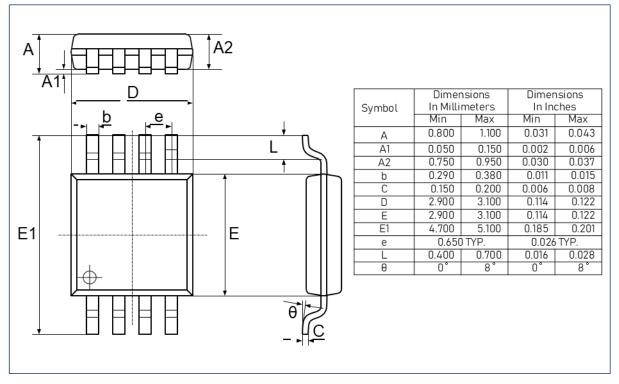


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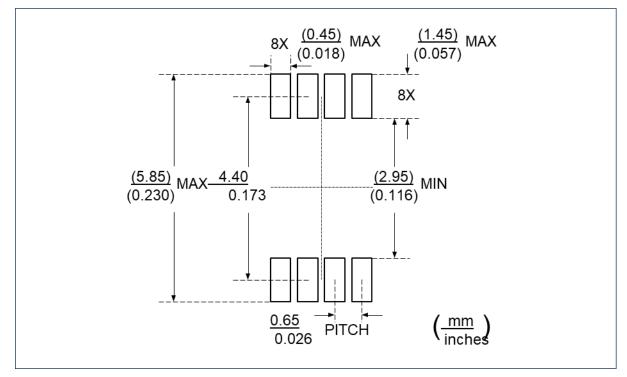
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## Package Outlines (cont.)

## DIMENSIONS, MSOP-8L



## RECOMMENDED SOLDERING FOOTPRINT, MSOP-8L



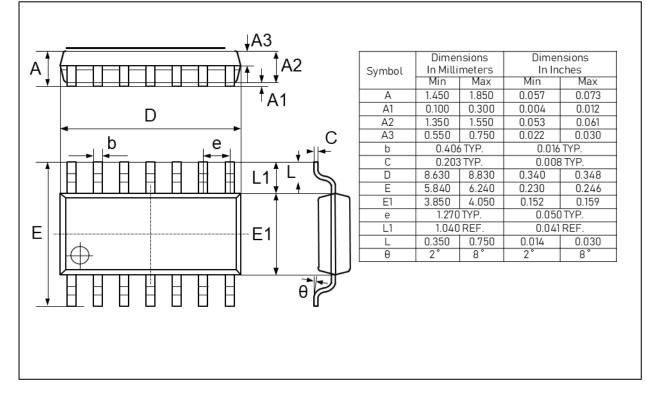
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# FN1624-24.0 — Data Sheet

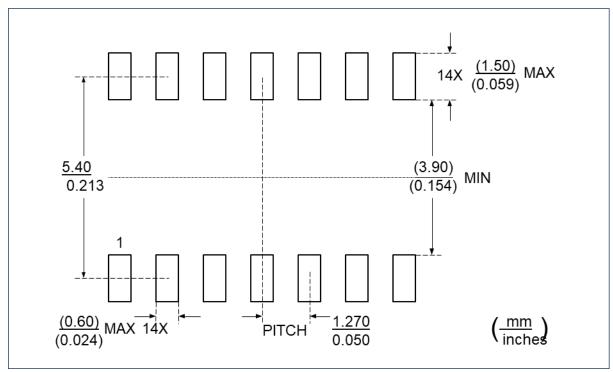
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## Package Outlines (Cont.)

## DIMENSIONS, SOIC-14L



### RECOMMENDED SOLDERING FOOTPRINT, SOIC-14L



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